Computer architectures

The Buses



What will it be about?

- Buses and related concepts
- Characteristics of famous buses

 Bus (bus, buses): Circuits and wires that conduct data traffic between individual functional units.



The Bus

- Three types of routes are possible between the main sub-components:
 - Between processor and memory;
 - Between processor and I/O devices;
 - Between memory and I/O devices
- But the circuits and wires that carry out the data traffic between the individual smaller functional components are also called Buses: we can talk about the internal buses of a CPU, the wires on a printed circuit board are buses, etc.



The Bus

- The bus: the set of circuits, wires and connectors that facilitate the flow of information between components (modules) and are necessary for system control.
- Functions:
 - To transport all bits of an n-bit word from a component connected to a bus to another component. Bits are mostly transferred in parallel.
 - They can be dedicated or split Buses: between two components or shared by several components (sharing!)



The bus (bus) - history

- In the case of the initial main-frames, two wires "bundle" from the processor to the memory, or to the devices. The processor handled the two "worlds" with separate instructions, different timings, and protocols. At first, it is not an interruption (interrupt IT) technique, but polling for the devices. Then IT emerged, with priorities. Daisy chain for peripherals. For multiprocessor systems, memory access is also solved with IT priorities.
- DEC's big idea: let the same bus handle both "worlds": UNIBUS
- Early PCs are also like this: The bus connected to the CPU legs leads to parallel sockets on the motherboard. Device control cards can be inserted into the sockets, memory chips into the memory socket. The CPU controls the bus. The controllers of the peripherals signal with IT, but the CPU "pushes" the data from their buffer into the memory.
- This simple bus system had a disadvantage: all components had to work at the same speed. Also: the bus could only be controlled by the CPU, instead of performing more useful tasks. Development: two worlds emerge: one is the CPU & memory, the other is the peripherals. Among them is the bus controller circuit. The CPU can work at a higher speed. The devices are able to communicate even without the supervision of the CPU, there is quite a lot of data transfer between the devices. The result was better overall performance. It was easier to build wider and wider (parallel) Buses, and to implement "plug-n-play" solutions instead of "setup" and "jumpering".
- The need for speed increased, the performance of the Buses brought starvation. The Buses were further "divided": SCSI, IDE, AGP, etc.



Bus classifications

- Scope (level).
 - Local Buses (usually non-standard, within a card, module, chip),
 - System Buses (between important system components, "backplane buses", mostly standard),
 - I/O level Buses (for connecting peripherals),
 - intersystem Buses (Buses connecting computers, usually standard, e.g. networks).
- The order of bit transmission
 - Parallel buses (each bit has its own line)
 - Serial buses (the lines carry a sequence of bits)



Bus classifications - in practice

- There can be "internal" buses that connect internal devices (e.g. memory, graphics card), and
- **"External" buses** for external devices (disks, scanner, camera, etc.). The internal Buses are sure to connect the components on the motherboard, while the device (controller) of the external bus can be on the motherboard or on an expansion card or port.
- **Parallel internal buses: EISA, PCI, local buses**
- Serial internal: 1-Wire, I²C, SPI (Serial Peripheral Interface Bus), PCI Express, HyperTransport
- **Parallel external: IDE (ATA), IEEE-488, PCMCIA (Personal Computer Memory Card Association), SCSI, Centronics parallel**
- Serial external: USB, FireWire



Logic classes of bus (lines).

- Data transfer dus
 - data bus,
 - address bus, address modifier bus.
 - (For these, an important characteristic is the bus width: the number of bits that can be transferred in parallel, the "number of lines")
- Arbitration bus (helps to resolve the conflict)
- Interrupt and sync bus
- Service bus



Logic classes of bus (lines). - another

- Data bus (Data Bus)
- Address Bus
- Control bus (Control Bus)
 - the data transfer control,
 - transmit interrupts,
 - controls synchronization,
 - transmits the bus control signals itself
- Signals controlling the data transfer can be:
 - the signal specifying the (memory I/O) data transfer *component*;
 - *read/write* indication;
 - *address strobe* signal (indicates the stable state of the address);
 - *data strobe* indication (data bus bits are stable);
 - *ready indication* (the device is available data transfer completed).



Terminology

- Module, component: device connected to the bus
- **Master** (active) module: able to initiate a bus operation and control the bus. There are potential masters.
- Slave (passive) module: able to respond
- Bus reservation (arbitration): a mechanism that selects one of those claiming the right to control the bus (since there can only be one master (controller) at a given time).
- Source (transmitter) and target (receiver) module
 If a slave module would like to be a source, it can only request the transfer (e.g. with interruption)





Terminology

- Bus transaction: sequence of activities (possibly time) between the occurrence of the bus request and the end of the transfer. It can include several operations (phases) (these may require several bus cycles):
 - bus request,
 - bus reservation (arbitration),
 - addressing (can be location-independent (individual), memory embedded and group),
 - data transfer,
 - error detection and error indication,
 - termination of the master's right.

Protocol: rules for correct execution of a transaction. Rules related to timing, control, format, data representation.



Terminology

Component addressing can be:

- Location-independent : Each device has a clear, unique address, it is not necessary to select the component (or group);
- Memory embedded addressing:
 I/O is addressed as memory, there is no separate peripheral instructions (peripheral operation).
 The memory and I/O address range coincide.
- Group addressing:
 - All passive units are addressed (e.g. reset all devices).



What does the bus standard mean?

• Electrical specifications

- the number of data and address lines,
- types and functions of control lines,
- signal levels, signal level changes,
- load capacity data, etc.
- Mechanical specifications
 - dimensions, connector types, connections, etc.
- Timing specifications etc.
- Protocols.



Let's note ...

- We often mark the buses with a line, but they are
 - circuits,
 - they also require time for signals to run.
 - They work in cycles and
 - levels (or level changes) appear after the transients.
- Electrical characteristics:
 - bus line drive circuits (bus drivers),
 - bus line receiver circuits,
 - transmission characteristics (finite signal propagation speed, distortions, etc.)
 - bus holder circuits (possibly),
 - power-down circuit (possibly).



Communication methods can be

- **Synchronous Buses** (transmission-reception at a given speed, with timed synchronization signals).
 - Devices connected to the bus use the same clock signal (clock edges) ;
 - Data is sent and received at the same speed ;
 - connection always exists, connect is not required;
 - acknowledgement is not required;
 - fast, but also requires line transmitting synchronisation;

• Asynchronous transmission (transmitter and receiver are not in sync, contact, acknowledgement of receipt is required).

- the speed of the components may be different;
- no permanent connection;
- acknowledgement can be done by handshake.



Bus performance

- Depends on the clock speed and cycle time of the bus,
- the bit width of the bus,
- the transmission protocol,
- the number of bus controllers: the time of the arbitration algorithm.
- (Arbitration: "competitive" assignment occurring in the case of more controllers.)



Control methods

- **Block transmission** (Burst Mode): data blocks are moving in a single bus operation.
- Dynamic bus width change
- Protocol switching



Basic concepts

- The two entities of the transfer are the *source* and the *destination*
- Any entity can be the *initiator*
 - Initiated by the source: writing;
 - Eg from CPU reg to mem. writing to a register
 - Initiated by the goal: <u>reading</u>
 - E.g. mem into CPU reg. reading from a register
- Conventional transmission:
 - Write : address1 + data1 + address2+ data2+ ...
 - Reading : address1 + address2+

-data1 -data2

Block transfer

- Writing :
 - start address+data1+data2+data3+ ...
- Reading :
 - start address+

-data1-data2-data3- ...

- "Saving" the address transfers
- consecutive addresses at the source,
- at the destination, the data comes/goes to consecutive addresses ...



Reading, writing

intel

8080A/8080A-1/8080A-2

WAVEFORMS

Tanszék



Famous Buses

- PC XT (1981) (XT: Extended Technology)
 - 8-bit data, 20-bit address, 7 interrupt requesting lines,
 4 direct memory access lines,
 - 4.77 MHz frequency, synchronous
 - can be only controlled by CPU and DMA on the motherboard,
 open standard.
- PC AT (1984) (AT: Advanced Technology), later ISA (ISA: Industry Standard Architecture)
 - 16-bit data (but also 8-bit cards), 24-bit address,
 15 interrupt requests, 8 direct memory access request lines,
 6 12.4 MHz clock frequency,
 - can also be controlled by an external unit,
 - open standard.

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ISA 8bit

Általános INFORMATIKAI Tanszék 8 Bit XT Bus - top view

			P	
GND	B 1		A 1	I/O CH CK
RESET DRV	B 2		A 2	Data 7
+5V	В 3		A 3	Data 6
IRQ 2	В 4		A 4	Data 5
-5V	В 5		A 5	Data 4
DRQ 2	B 6		A 6	Data 3
-12V	В 7		A 7	Data 2
Reserved, NC	B 8		A 8	Data 1
+12V	В 9		A 9	Data 0
GND	B 10	i t i	A 10	I/O CH RDY
MEMW	B 11		A 11	AEN
MEMR	B 12		A 12	Addr 19
IOW	B 13		A 13	Addr 18
IOR	B 14		A 14	Addr 17
DACK 3	B 15		A 15	Addr 16
DRQ 3	B 16		A 16	Addr 15
DACK 1	B 17		A 17	Addr 14
DRQ 1	B 18		A 18	Addr 13
DACK 0	B 19		A 19	Addr 12
CLK	B 20		A 20	Addr 11
IRQ 7	B 21		A 21	Addr 10
IRQ 6	B 22		A 22	Addr 9
IRQ 5	B 23		A 23	Addr 8
IRQ 4	B 24		A 24	Addr 7
IRQ 3	B 25		A 25	Addr 6
DACK 2	B 26		A 26	Addr 5
T/C	B 27		A 27	Addr 4
ALE	B 28		A 28	Addr 3
+5V	B 29		A 29	Addr 2
osc	B 30		A 30	Addr 1
GND	B 31		A 31	Addr 0

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ISA 16bit

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16 Bit ISA Bus – top view				
/		_	\	
GND	B 1		A 1 NO CH CK	
RESET DRV	B 2		A 2 Data 7	ו
+5V	B 3		A 3 Data 6	
IRQ 9	B 4		A 4 Data 5	
-5V	B 5		A 5 Data 4	
DRQ 2	B 6		A 6 Data 3	
-12V	В 7		A 7 Data 2	
Reserved, NC	B 8		A 8 Data 1	
+12V	B 9		A 9 Data 0	
GND	B 10		A 10 1/0 CH KDT	
MEMW	B 11 B 12		A 12 Addr 19	
	B 13		A 12 Addr 19	
	B 14		A 13 Addr 18	
DACK 3	B 15		A 15 Addr 16	
8 Bit XT-Bus - DRQ 3	B 16		A 16 Addr 15	
DACK 1	B 17		A 17 Addr 14	
DRQ 1	B 18		A 18 Addr 13	
REFRESH	B 19		A 19 Addr 12	
CLK	B 20		A 20 Addr 11	
IRQ 7	B 21		A 21 Addr 10	
IRQ 6	B 22		A 22 Addr 9	
IRQ 5	B 23		A 23 Addr 8	
IRQ 4	B 24		A 24 Addr 7	
IRQ 3	B 25		A 25 Addr 6	
DACK 2	B 26		A 26 Addr 5	16 Bit ISA-Bus
I ^{T/C}	B 27		A 27 Addr 4	
I ALE	B 28		A 28 Addr 3	
+50	B 29		A 29 Addr 2	
\ GND	B 31		A 30 Addr 1	
	0.01		A 31 Addi U	
``\				
MEM CS 16	D 1		C 1 SBHE	
1/0 CS 16	D 2		C 2 Addr 23	
IRQ 10	D 3		C 3 Addr 22	
IRQ 11	D 4		C 4 Addr 21	
IRQ 12	D 5		C 5 Addr 20	
IRQ 15	D 6		C 6 Addr 19	
IRQ 14	D 7		C 7 Addr 18	
DACK 0	D 8		C 8 Addr 17	
DRQ 0	D 9		C 9 MEMR	
DACK 5	D 10		C 10 MEMW	
DRQ 5	D 11	┝═╋═┥	C 11 Data 8	
DACK 6	D 12		C 12 Data 9	
DACK 7	D 14		C 14 Data 10	
DRG 7	D 15		C 14 Data 11	
+51/	D 16		C 16 Data 13	
MASTER	D 17		C 17 Data 14	
GND	D 18		C 18 Data 15	,
	0.000			

Famous buses...

- EISA (Extended Industry Standard Architecture)
 - specified by several (9) companies,
 - 32/32-bit (but also accepts 8/16-bit cards), multi-master, burst mode transmission,
 - open standard with precise timing specifications,
 - 8 MHz, 32 MB/s
- IBM MCA (Micro Channel Architecture) (1987)
 - (16) 32/32 bits, 10 MHz,
 - not compatible with ISA, EISA Buses,
 - software configuration,
 - not an open standard!

The PCI bus

Led by Intel: Peripheral Component Interconnect (1992, 93:2.0, 95: PCI 2.1)

- Synchronous bus; 5 (or 3.3) V extension connectors;
- First: 32 bits, 33 MHz, (4*33=132 MB/s)
- PCI 2.0: 64-bit, 33 MHz
- PCI 2.1: 64 bit, 66 MHz (524 MB/s theoretically).
- PCI-X: 133MHz (1066MB/s)
- PCI-X 2.0: 266MHz, larger configuration memory (2133 MB/s)
- There are no separate address and data wires! Losses are higher with non-block transmission!
- Practically 50-80% performance.
 - From 1995-96, its distribution widens, until 2000 approx. same as ISA-EISA bus.
 - From 95, Apple replaces the NuBus bus with PCI.
 - In 2004, its serial version appeared: PCI Express
 - Other versions: Mini PCI, for laptops

The PCI bus

- Additional benefits:
 - compatibility with 32-bit peripherals,
 - -processor independent!
 - There is no need to "setup" the cards!
 - Shared connectors too! (This was important until 2000!)
- Many companies use it, even abandoning their own bus concept. For both client machines and servers!



PCI



Architecture based on PCI bus



The so-called PCI *mezzanine* bus: located between the CPU bus and the system bus.



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The bus systems of a "modern" PC...



Today, PCI bandwidth is no longer enough for graphics. Intel: Mid 90s: AGP (Accelerated Graphic Port) From 2004, the serial version of PCI: PCI Express

... and a functional block diagram of the Intel 815 chipset ...



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PCI Express

- Between 1991 and 2004, the PCI was valid
 - From 1997, the AGP "helped out"
- Demand continued to grow
- **PCIe** : on both Intel and AMD motherboards
 - serial, point-to-point bus
 - **–** Scalable (lane: 4 pin width data paths can be multiplied)
 - x1, x4, x8, x16, x32

PCle	Lanes	Pins	MB/s	Purpose
x1	1	4	500 MB/s	Device
x2	2	8	1000 MB/s = 1 GB/s	Device
x16	16	64	8000 MB/s = 8 GB/s	Graphics Card



	Pin	Side B	Side A	Comments
	1	+12V	PRSNT1#	Pulled low to indicate card inserted
	2	+12V	+12V	
	3	Reserved	+12V	
	4	Ground	Ground	
	5	SMCLK	ТСК	1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (1977 (19
	6	SMDAT	TDI	SMBus and
	7	Ground	TDO	JTAG port pins
	8	+3.3V	TMS	11
	9	TRST#	+3.3V	
	10	+3.3 Vaux	+3.3V	Standby power
	н	WAKE#	PWRGD	Link reactivation, power good.
	Key notch			
	12	Reserved	Ground	
	13	Ground	REFCLK+	Reference clock differential pair
	14	HSOp(0)	REFCLK-	Lane 0 transmit
	15	HSOn(0)	Ground	data, + and –
	16	Ground	HSIP(0)	Lane 0 receive
	17	PRSNT2#	HSIn(0)	data, + and –
	18	Ground	Ground	
	10		Posorvod	
	20		Currend	Lane I transmit
	20	HSOn(1)	Ground	data, + and -
	21	Ground	HSIP(1)	Lane 1 receive
	22	Ground	HSIn(1)	data, + and –
	23	HSOp(2)	Ground	Lane 2 transmit
	24	HSO(2)	Ground	data, + and –
	25	Ground	HSIP(2)	Lane 2 received
	26	Ground	HSIn(2)	data, + and –
	27	HSOp(3)	Ground	I and 3 transmit
	28	HSOn(3)	Ground	data. + and –
	29	Ground	HSIn(3)	
	30	Bosorvod	HSIp(3)	Lane 3 received
talános		DENT2"	Crossed	
FORMATIKA		PRSN12#	Ground	
		Ground	Keserved	

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PCI Express x4



x4, ×16, ×1, ×16, 32-bit PCI

Ea 631

Other famous Buses: ATA

- Advanced Technology Attachment: for external parallel bus disks, CD-ROM connection
- Acronyms: IDE (Integrated Drive Electronic), EIDE (Enhanced IDE), ATAPI (ATA Packet Interface), UDMA (Ultra Direct Memory Access).
- Serial ATA was introduced in 2003, the name PATA (Parallel ATA) was retroactively given

• Reasons for size limits (504 MB, 8 GB, 32 GB, 137 GB):

- The original ATA specification used 28-bit addressing.
- This would have allowed 137GB, but the standard BIOS of the time could only handle 8 GB. But the situation was worse, bringing the IDE and BIOS to the common denominator with the then CHS (Cylinder-Head-Sector) addressing gave only 512MB. LBA (Logical Block Addressing 48 bits) introduced system, the limit could already rise to 8GB. It could then rise over time.



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ATA

- 40-pin connectors (three) on a 40line flat cable (with the appearance of UDMA, the cable has 80 wires, but the connector is 40).
- Cable max. 46 cm long: this makes it difficult to assemble large systems
- One cable can have a master and a slave device (device 0 and device 1)



- The device driver of the OS "manages" the arbitration: if device 1 executes a "command", device 0 cannot start a command (a slower CD can slow down the HD next to it)
 - The ATA controller is on the motherboard.
 Two channels (channell): primary and secondary



Pin 1	Reset
Pin 2	Ground
Pin 3	Data 7
Pin 4	Data 8
Pin 5	Data 6
Pin 6	Data 9
Pin 7	Data 5
Pin 8	Data 10
Pin 9	Data 4
Pin 10	Data 11
Pin 11	Data 3
Pin 12	Data 12
Pin 13	Data 2
Pin 14	Data 13
Pin 15	Data 1
Pin 16	Data 14
Pin 17	Date 0
Pin 18	Data 15
Pin 19	Ground
Pin 20	Key or VCC_in
Pin 21	DDRQ
Pin 22	Ground
Pin 23	I/O write
Pin 24	Ground
Pin 25	I/O read
Pin 26	Ground
Pin 27	IOCHRDY
Pin 28	Cable selection
Pin 29	DDACK
Pin 30	Ground
Pin 31	IRQ
Pin 32	No connection
Pin 33	Addr 1
Pin 34	GPIO_DMA66_De
Pin 35	Addr 0
Pin 36	Addr 2
Pin 37	Chip select 1P
Pin 38	Chip select 3P
Pin 39	Activity
Pin 40	Ground



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-ATA

ATA standards and features

Name	Another name	New features	ANSI Reference
ATA-1	ATA, HERE	up to 528 MB	X3.221-1994 (obsolete since 1999)
ATA-2	EIDE, Fast ATA, Fast IDE, Ultra ATA	24-bit LBA (up to 8.4 GB)	X3.279-1996 (obsolete since 2001)
ATA-3	EIDE	28-bit LBA (up to 137 GB) SMART, Security	<u>X3.298-1997</u> (obsolete since 2002)
ATA-4	ATAPI-4, ATA/ATAPI-4	Support for CD-ROM, etc., via ATAPI packet commands	NCITS 317-1998
ATA-5	ATA/ATAPI-5	80-wire cables	NCITS 340-2000
ATA-6	ATA/ATAPI-6	48-bit LBA (up to 144 TB) Automatic Acoustic Management	NCITS 347-2001
ATA-7	ATA/ATAPI-7		NCITS 361-2002
ATA-8	ATA/ATAPI-8		in project
Atalános NFORMATI	1.0 SATA: 150Mb	The buses © Vadász, 2007. ops, 2.0 SATA: 300Mbps	Ea 635

Serial ATA (SATA)

Serial ATA (Serial Advanced Technology Attachment)

- SATA revision 1.0 (SATA 1.5 Gbit/s), (SATA/150), 2003 :
 - 1.5 Gbit/s (8b/10b encoding overhead)
 - max. uncoded transfer rate 1.2 Gbit/s (150 MB/s)
 - SATA/150 \approx SATA/133
- SATA revision 2.0 (SATA 3 Gbit/s), (SATA/300), 2004 :
 - 3 Gbit/s
 - max. uncoded transmission speed 2.4 Gbit/s (300 MB/s)
 - SATA/150 compatible
- SATA revision 3.0 (SATA 6 Gbit/s), (SATA/600), 2008 :
 - 6 Gbit/s, max. uncoded transmission speed 4.8 Gbit/s (600 MB/s)
- SATA revision 3.2 (SATA 16 Gbit/s), (SATA/1600), 2013 :
 - 16 Gbit/s, max. unencoded transfer rate 1969 MB/s



Serial ATA (SATA)

Serial ATA (Serial Advanced Technology Attachment)

Pin #	Function	Pin #	Function
1	Grounding	1–3	3.3V
2	A+	4-6	Grounding
3	А-	7–9	5V
<u>л</u>	Grounding	10	Grounding
-	Grounding		Delayed start
5	B-	11	(only in suppor drives)
6	B+	12	Grounding
7	Grounding	13–1:	5 12V



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Hot swap



max. 1m cable



Ea 637

Serial ATA (SATA)

SATA Pinout - Plug









Something about performance...



http://www.tomshardware.com/storage/20020806/ide-08.html#benchmarks

2010 : 10,000 rpm SATA hard disk maximum data transfer rate up to 157 MB/s 2015 : disk hardware : 0.7-1.3 MB/s , SSD : 25-70 MB/s , cache : 200-400 MB/s 2022: NVMe SSD Sequential Read 7000 MB/s Sequential Write 5000 MB/s Random Read 1000 MB/s Random Write 700 MB/s non-volatile memory, PCI Express bus Solid-state drive (SSD), Solid-state hybrid drive (SSHD)

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More famous Buses

- SCSI (Small Computer System Interface) (from 1981)
 SCSI-1 (1986)
 - SCSI-2 (Wide, Fast SCSI) (1989)
 - SCSI-3 (1992)
- Max. 8 (16) devices can be connected (but only 2 can communicate)
 - initiator (can be the computer) and the target device (this can be a peripheral or even another machine),
 - (multi-master arbitration).
 - Cable length: 6m (25 m), 50-pin connectors.



SCSI interface summary

Interface	Bit width	Clock signal	bus bandwidth	Max. cable length	Max. number of devices
SCSI	8 bits	5 MHz	5 MB/s	6 m	8
Fast SCSI	8 bits	10 MHz	10 MB/s	1.5-3m	8
Wide SCSI	16 bits	10 MHz	20 MB/s	1.5-3m	16
Ultra SCSI	8 bits	20 MHz	20 MB/s	1.5-3m	5-8
Ultra Wide SCSI	16 bits	20 MHz	40 MB/s	1.5-3m	5-8
Ultra2 SCSI	8 bits	40 MHz	40 MB/s	12 m	8
Ultra2 Wide SCSI	16 bits	40 MHz	80 MB/s	12 m	16
Ultra3 SCSI	16 bits	40 MHz DDR	160 MB/s	12 m	16
Ultra-320 SCSI	16 bits	80MHz DDR	320 MB/s	12 m	16



Another famous bus: USB

USB 2.0

- Universal Serial Bus
 - USB control and distribution (hub) system on the host (devices can be connected in a tree structure, max. 5 depth)
 - Also power supply on 5 m cable
- Advanced plug-n-play capabilities
- Many types of devices can be connected (mouse, keyboard, scanner, camera, printer, HD, flash memory, network, etc.) device classes





USB device classes USB Human interface device class: mouse, keyboard (Low Speed Rate: 1.5 Mbps) **USB Mass storage device class:** Keydrives, HD, Cards, cameras, audio players (Full Speed Rate: 12 Mbps, or *Hi-Speed Rate: 480 Mbps*) **USB communication devices class (CDC):** modem, network cards, ISDN, Fax **USB printer device class: USB audio device class:** sound card type device **USB video device class:** webcam, video cam



USB

- Devices are connected to the host (host controller) via the USB bus
- Tools functions. The hub has no official function

 All devices/functions are identified
- The endpoint: the function away from the host
- A pipe is formed from the host to the endpoint.
 32 active channels for endpoints: 16 inward,
 16 outward (in and out are defined from the host's point of view)
- Packag sizes are varying on the channels



USB

- 4 data transmission types on the channels
 - *Control*. Bidirectional, commands to the device, status information to the host
 - *Interruption*. One-way transmission, for devices that require fast reactions (mouse, keyboard, joystick)
 - *Isochron.* One-way, guaranteed speed devices where a package can be lost (telephone, speaker, realtime video, etc.)
 - Bulk. Two-way, for transferring large amounts of data, no delay guarantee, but with acknowledgement (file transfer)



USB

Three transmission speeds

- Low Speed Rate : 1.5 Mbps.
 Mainly for HiD (Human Interface Devices).
- Full Speed Rate : 12 Mbps.
 Before USB 2.0, this was the maximum
- Hi-Speed Rate : 480 Mbps. Only from USB 2.0.
- The USB connectors

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- Type A and B, not interchangeable (no circle)
- 4 wires (Power, D+, D-, Earth).
 Twisted pair, shielded is better.
- Power: 5 V, 500 mA. It may not be enough for a device that requires high performance



USB versions

- USB 1.0 FDR Nov 1995
- USB 1.0 Jan 1996
- USB 1.1 Sep 1998
- USB 2.0 Apr 2000
 - HI- Speed Mode
- USB 2.0 revised Dec. 2002
 - All three rates, backwards compatibility
- USB 3.0 2008
 - 5 Gbps (1.5A (5V, 7.5W), 5A (20V, 100W) Battery Charging Specification)
- USB 3.1 2013
 - 10 Gbps
- USB 3.2 2017
 - 20 Gbps
- USB 4 2019 only USB C
 - 20 Gbps DisplayPort and PCI Express tunneling

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USB versions : USB 3.0

USB 3.0 connector pinouts^[51]

Din	Color	Signal name		Description				
ГШ	COIOI	A connector	B connector	Description				
Shell	N/A	Shield		Metal housing				
1	Red	VB	US	Power				
2	White	D	 :					
3	Green	D	+	USB 2.0 dillerential pair				
4	Black	GI	ND	Ground for power return				
5	Blue	StdA_SSRX-	StdB_SSTX-	SuperSpeed receiver differential pair				
6	Yellow	StdA_SSRX+	StdB_SSTX+	SuperSpeed receiver differential pair				
7	N/A	GND_I	DRAIN	Ground for signal return				
8	Purple	StdA_SSTX-	StdB_SSRX-	SuperSpeed transmitter differential pair				
9	Orange	StdA_SSTX+	StdB_SSRX+	SuperSpeed transmitter differential pair				
The US	B 3.0 Powe	ered-B connector h	as two additional	pins for power and ground supplied to the device. ^[52]				
10			DPWR	Power provided to device (Powered-B only)				
11	N/A		DGND	Ground for DPWR return (Powered-B only)				
ltalános NFORMA Ta	talános The buses © Vadász, 2007. Ea 648 FORMATIKAI https://en.wikipedia.org/wiki/USB_3.0 Ea 648							

USB versions : USB 3.0



https://en.wikipedia.org/wiki/USB_3.0



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USB versions : USB C

	1	ype-C receptacle A pin layout		Type-C receptacle B pin layout		
Pin	Name	me Description		Name	Description	
A1	GND	Ground return	B12	GND	Ground return	
A2	SSTXp1	SuperSpeed differential pair #1, TX, positive	B11	SSRXp1	SuperSpeed differential pair #2, RX, positive	
A 3	SSTXn1	1 SuperSpeed differential pair #1, TX, negative B10 SSRXn1 SuperSpeed differential pair #2, RX,				
A4	V _{BUS}	Bus power	B9	V _{BUS}	Bus power	
A 5	CC1	Configuration channel	B 8	SBU2	Sideband use (SBU)	
A6	Dp1	USB 2.0 differential pair, position 1, positive	B 7	Dn2	USB 2.0 differential pair, position 2, negative ^[a]	
A7	Dn1	USB 2.0 differential pair, position 1, negative	B6	Dp2	USB 2.0 differential pair, position 2, positive ^[a]	
A 8	SBU1	Sideband use (SBU)	B 5	CC2	Configuration channel	
A 9	V _{BUS}	Bus power	B4	V _{BUS}	Bus power	
A10	SSRXn2	SuperSpeed differential pair #4, RX, negative	B3	SSTXn2	SuperSpeed differential pair #3, TX, negative	
A11	SSRXp2	SuperSpeed differential pair #4, RX, positive	B2	SSTXp2	SuperSpeed differential pair #3, TX, positive	
A12	GND	Ground return	B1	GND	Ground return	

https://en.wikipedia.org/wiki/USB-C

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Tanszék





Other famous buses: FireWire

FireWire

- FireWire (IEEE 1394) (1995), i.Link
 - External serial bus of PCs (and isochronous devices).
 - Apple development. Sony: i.Link
- IEEE-1394a 2000.
- IEEE-1394b 2002.
- Fire Wire: 63 devices, hub
 - Multiple hosts (and no special chipset required for IP)
 - Devices can communicate without a CPU (peer-to-peer)
 - Plug-n-play support
 - Unregulated 25V (9 12V), 7 8 W load per port



FireWire versions

- FireWire 400
 - 100, 200, 400 Mbps speeds (in practice slightly lower: 98, 196, 392)
 - Cable length 4.5 m, but 16 devices can be chained together
 (daisy chain)
 - 6 or 4-pin connector, cable
- FireWire 800 (2003)
 - 786 Mbps, but compatible with 400 Mbps devices
 - 9-pin connector





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Comparison

\$	Nyers sávszélesség (Mbit/s) ◆	Átviteli sebesség (MB/s) ◆	Max. kábel hossz. (m) ♦	Áramot közvetít 🖨	Eszköz per csatorna 🗢	
SAS	3000	300	8	Nem	4	
eSATA	3000	300	2	Nem	1 (15 port sokszorosítóval)	
SATA 3	6000	600	1	Nem	1 per vonal	
SATA 2	3000	300	1	Nem	1 per vonal	
SATA 1	1500	150	1	Nem	1 per vonal	
PATA 133	1064	133	0,46	Nem	2	
FireWire 800	786	98	4,5 ^[1]	lgen (12–25 V, 15 W)	63	
FireWire 400	393	49	4,5 ^[1]	lgen (12–25 V, 15 W)	63	
USB 2.0	480	≈ 40	5 ^[2]	Igen (5 V, 2,5 W)	127	
USB 3.0	4800	?	?	Igen (5 V, 2,5 W)	127	
Ultra-320 SCSI (Ultra-4)	2560	320	12	Nem	16	
Ultra-640 SCSI (Ultra-5)	5120	640	??	Nem	16	
Fibre Channel rézkábelen	4000	400	12	Nem	126 (16777216 <mark>switch-csel</mark>)	
Fibre Channel optikán	10520	2000	2–50 000	Nem	126 (16777216 switch-csel)	
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FORMATIKAI Tanszék	http://hu.wikipedia.org/wiki/Serial_ATA					